# Quantifying the quality of forecasts and forecasting systems 

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## Outline

Overview of verification
Aspects of forecast quality
Uncertainty in verification

Verification for extreme events
A probability model
Application to rainfall forecasts

Conclusion

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## Aspects of forecast quality: bias

Unbiased


Biased


## Aspects of forecast quality: calibration




## Aspects of forecast quality: sharpness




## Mean squared error (MSE)

MSE = variance of observations + variance of forecasts $-2 \times$ covariance + squared bias
$=$ calibration - resolution + variance of observations



## Signal detection theory: ROC analysis

Forecast event if decision variable exceeds threshold.


## Properties of verification scores

Proper Expected score is optimised by forecasting true, probabilistic belief: discourages hedging.

Consistent Proper, for scores of deterministic forecasts derived from probabilistic forecasts via a rule.

Equitable Expected score is identical for all constant or random forecasts.

Sufficient Forecasts, from which others with equal quality to mine can be derived, score better than mine.

Regular Contours of score on ROC diagram are convex, complete, and pass through $(0,0)$ and (1,1).

Local
Score depends on the forecasted probability of the observation only.

## How should/do we use verification measures?

Forecast producers

- Systematic assessment can reveal deficiencies...
... and possible remedies.
- Prevent hedging: what, why, how?

Forecast users

- Some measures can relate directly to value...
... perhaps more links can be established.
- How are decisions influenced by overall forecast quality?


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## Uncertainty in verification

Incomplete information

- Assume the sample represents the population
- Compute confidence intervals etc. for the 'true' quality
- Avoid using the same data to form and assess forecasts



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## Uncertainty in verification

Incomplete information

- Better methods for quantifying uncertainty
- What if forecast quality is not stationary?

Observation error
Quality of untried forecasting systems
Quality of systems in untried situations
Other sources of uncertainty?

## Summary

- Various aspects of forecast quality
- Careful use of appropriate measures
- Faithful description of uncertainty


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## Direct approach

Observed Not Obs.

| Forecasted | $a$ | $b$ | $a+b$ |
| ---: | :---: | :---: | :---: |
| Not Forecasted | $c$ | $d$ | $c+d$ |
|  | $a+c$ | $b+d$ | $n$ |

Hit rate $=\frac{a}{a+c}$

Forecast if $X>u$
Observe if $Y>v$


## Probability approach

## Observed Not Obs.

| Forecasted | $\operatorname{Pr}(X>u, Y>v)$ | $*$ | $\operatorname{Pr}(X>u)$ |
| ---: | :---: | :---: | :---: |
| Not Forecasted | $*$ | $*$ | $*$ |
|  | $\operatorname{Pr}(Y>v)$ | $*$ | 1 |

Hit rate $=\operatorname{Pr}(X>u \mid Y>v)$

Forecast if $X>u$
Observe if $Y>v$


## Probability model

Imagine choosing $u$ so that

$$
\operatorname{Pr}(X>u)=\operatorname{Pr}(Y>v)=: p \quad \text { (base rate) }
$$

Extreme-value theory implies

$$
\operatorname{Pr}(X>u, Y>v)=\kappa p^{1 / \eta} \quad \text { for small } p
$$

under weak conditions.

## Interpretation

## Observed Not Observed

| Forecasted | $\kappa p^{1 / \eta}$ | $*$ | $p$ |
| ---: | :---: | :---: | :---: |
| Not Forecasted | $*$ | $1-2 p+\kappa p^{1 / \eta}$ | $*$ |
|  | $p$ | $*$ | 1 |

Hit rate $=\kappa p^{1 / \eta-1}$

$\kappa_{2} \kappa_{1}$| Superior <br> for $p>p^{*}$ |
| :---: |
| Inferior <br> for all $p$ |
| 0 | | Superior |
| :---: |
| for all $p$ |\(\left|\begin{array}{c}Superior <br>

for p<p^{*}\end{array}\right|\)

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## Daily rainfall: mid-Wales, 1 Jan 05-11 Nov 06

## Thanks to Marion Mittermaier



- Maximum-likelihood estimates of $\eta$ and $\kappa$ based on ranks
- Threshold choice and model assumptions


## Parameter estimates



## Verification measures



- Direct estimates degenerate for rare events
- Model estimates change smoothly and are more precise


## Summary

- Deterministic forecasts of rare, extreme events
- Only two parameters needed to describe how quality or value of calibrated forecasts changes with base rate
- The model gives more precise estimates of forecast quality


## Conclusion

- Statistical models help to identify and measure aspects of forecast quality, their changes and associated uncertainty.
- Why/how should/do producers/users use/do verification?
- Are current methods and procedures adequate?
- Can we verify the quality of decisions?

Papers, code and slides available at
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## Appendix

Simulation study

Model theory

Limiting behaviour of verification measures

## Simulation study

- Bivariate Normal data: correlation 0.8
- Direct and model estimates of hit rate





## Model theory - 1

Imagine choosing $u$ so that

$$
\operatorname{Pr}(X>u)=\operatorname{Pr}(Y>v)=: p \quad \text { (base rate). }
$$

Define $\quad \tilde{X}=-\log [1-F(X)]$ where $F(x)=\operatorname{Pr}(X \leq x)$

$$
\tilde{Y}=-\log [1-G(Y)] \quad G(y)=\operatorname{Pr}(Y \leq y)
$$

Then $\tilde{X}$ and $\tilde{Y}$ are Exponential with unit means and

$$
\begin{aligned}
\operatorname{Pr}(X>u, Y>v) & =\operatorname{Pr}(\tilde{X}>-\log p, \tilde{Y}>-\log p) \\
& =\operatorname{Pr}(Z>-\log p)
\end{aligned}
$$

where $Z=\min \{\tilde{X}, \tilde{Y}\}$.

## Model theory - 2

For $\tilde{X}$ and $\tilde{Y}$ Exponential with unit means and $Z=\min \{\tilde{X}, \tilde{Y}\}$,

$$
\operatorname{Pr}(Z>z)= \begin{cases}\exp (-z) & \text { if } \tilde{X} \equiv \tilde{Y} \\ \exp (-2 z) & \text { if } \tilde{X} \Perp \tilde{Y}\end{cases}
$$

Assume

$$
\operatorname{Pr}(Z>z) \sim \mathcal{L}\left(e^{z}\right) \exp (-z / \eta) \quad \text { as } z \rightarrow \infty,
$$

where $0<\eta \leq 1$ and $\mathcal{L}(r t) / \mathcal{L}(r) \rightarrow 1$ as $r \rightarrow \infty$ for all $t>0$.
e.g. $(X, Y) \sim$ Normal has $\eta=[1+\operatorname{cor}(X, Y)] / 2$.

Ledford \& Tawn (1996, Biometrika)

## Model theory - 3

$\operatorname{Pr}(Z>z) \sim \mathcal{L}\left(e^{z}\right) \exp (-z / \eta)$ where $\mathcal{L}(r t) / \mathcal{L}(r) \rightarrow 1$ as $r \rightarrow \infty$.

For a high threshold $w_{0}$,

$$
\begin{aligned}
\operatorname{Pr}\left(Z>w_{0}+z\right) & \approx \mathcal{L}\left(e^{w_{0}+z}\right) \exp \left[-\left(w_{0}+z\right) / \eta\right] \\
& \approx \mathcal{L}\left(e^{w_{0}}\right) \exp \left[-\left(w_{0}+z\right) / \eta\right]
\end{aligned}
$$

so model

$$
\operatorname{Pr}(Z>z)=\kappa \exp (-z / \eta) \quad \text { for all } z>w_{0}
$$

i.e.

$$
\operatorname{Pr}(Z>-\log p)=\kappa p^{1 / \eta} \quad \text { for all } p<\exp \left(-w_{0}\right)
$$

## Limiting behaviour of measures

Hit rate $=\frac{a}{a+c} \sim \kappa p^{1 / \eta-1} \rightarrow \begin{cases}0 & \text { if } \eta<1 \\ \kappa & \text { if } \eta=1\end{cases}$


## Limiting behaviour of measures

$$
\text { Hit rate }=\frac{a}{a+c} \sim \kappa p^{1 / \eta-1} \rightarrow \begin{cases}0 & \text { if } \eta<1 \\ \kappa & \text { if } \eta=1\end{cases}
$$

$$
\mathrm{PC}=\frac{a+d}{n}, \quad \mathrm{PSS}=\frac{a d-b c}{(a+c)(b+d)}, \quad \mathrm{OR}=\frac{a d}{b c}
$$

## Limiting behaviour of measures

Hit rate $=\frac{a}{a+c} \sim \kappa p^{1 / \eta-1} \rightarrow \begin{cases}0 & \text { if } \eta<1 \\ \kappa & \text { if } \eta=1\end{cases}$

$$
\mathrm{PC}=\frac{a+d}{n}, \quad \mathrm{PSS}=\frac{a d-b c}{(a+c)(b+d)}, \quad \mathrm{OR}=\frac{a d}{b c}
$$

| $\eta<\frac{1}{2}$ |  | $\eta=\frac{1}{2}$ | $\eta>\frac{1}{2}$ | $\eta=1$ |
| :--- | ---: | ---: | ---: | ---: |
| PC | $1-2 p \uparrow 1$ | $1-2 p \uparrow 1$ | $1-2 p \uparrow 1$ | $1-2 \bar{\kappa} p \uparrow 1$ |
| PSS | $-p \uparrow 0$ | $-\bar{\kappa} p \uparrow 0$ | $\kappa p^{\delta-1}$ | $\downarrow 0$ |
| OR | $\kappa p^{\delta-2} \downarrow 0$ | $\kappa-2 \kappa \bar{\kappa} p \downarrow \kappa$ | $\kappa p^{\delta-2} \uparrow \infty$ | $\kappa /\left(\bar{\kappa}^{2} p\right) \uparrow \infty$ |

where $\delta=1 / \eta$ and $\bar{\kappa}=1-\kappa$

## Contradictory skill scores?

ERA-40 daily rainfall forecasts: $\eta=0.81, \kappa=1.16$


