

Outline



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Why parallelism?

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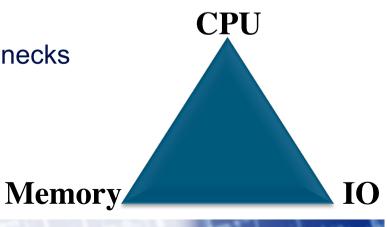
- It takes one brick layer 3 days to lay a wall
 - How long will it take 3 brick layers?
 - Opportunity to do things faster or bigger
- Can use multi-core systems in the same way
 - Most laptops now come with multiple core systems
 - Can take advantage of computers on a network
 - Communications latencies may prove expensive
 - Can used dedicated parallel machines (e.g. HECToR)
 - Have fast communication interconnects
- Main parallelisation strategies:
 - OpenMP (multi-threading) shared memory machines
 - MPI explicit message passing
 - Can use both
- Beatbox uses MPI



Some background



- Beatbox scripts are agnostic as to whether they are:
 - Run serially
 - Run in parallel
- Beatbox is currently not memory or I/O constrained.
 - Issues more to do with obtaining enough CPU power
 - Impacts on the parallelisation strategy used
 - Domain decomposition used
- Need to determine how well the parallel code works
 - See how well it scales
 - Dive down to identify performance bottlenecks



Performance metrics: speed-up & efficiency



• Speed-up S_n:

$$S \downarrow n = T \downarrow 1 / T \downarrow n$$

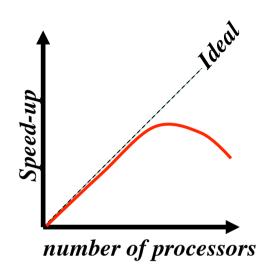
- Where:
 - T₁ is the execution time on 1 processor
 - T_n is the execution time on n processors
- Parallel Efficiency E_n:

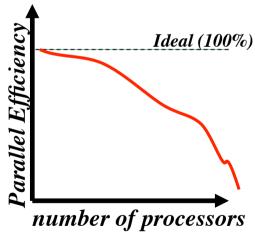
$$E \downarrow n = S \downarrow n / n$$





Weak scaling: fixed problem size per processor

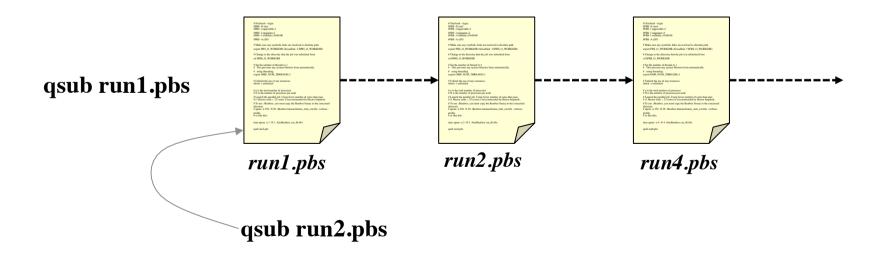




Methodology: scalability curves



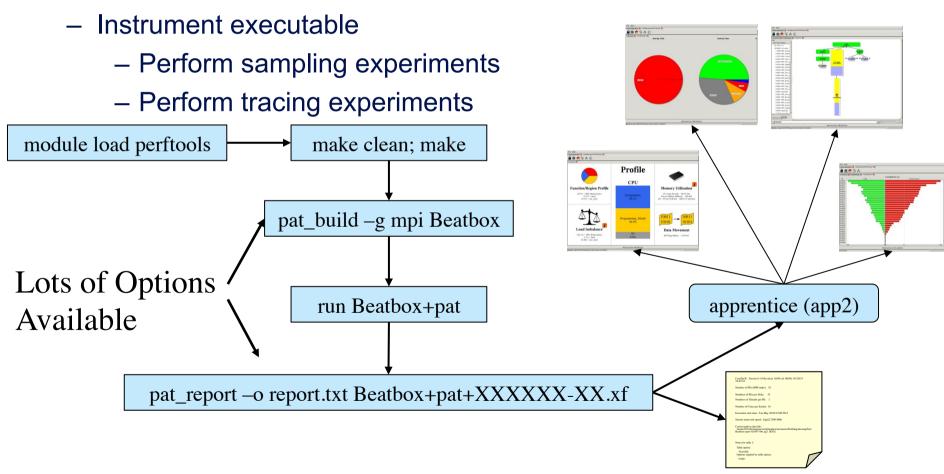
- Use chained PBS (Portable Batch System) scripts
 - PBS is the scheduling/batch system that operates on HECToR
- Could use shell script loops but max run time is 12 hours
 - Total run time for all the scripts can exceed that
- Variance not high so run jobs only once



Methodology: profiling

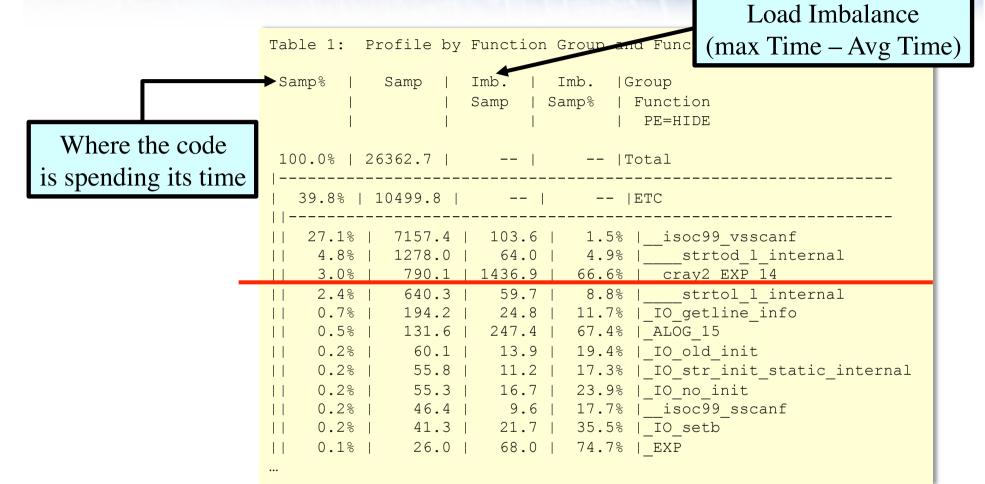


- Instrument the code to find out where it is spending time
 - Identify bottlenecks
- Cray Performance Analysis Tools (PAT)



Profiling: example output



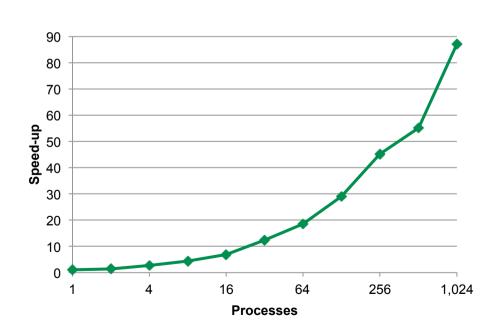


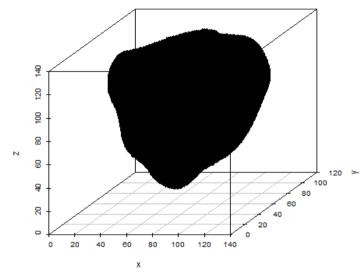
- Identify expensive parts
 - See if performance can be improved
- Caveat: don't want to optimise just one code execution path
 - Use different configurations/data files

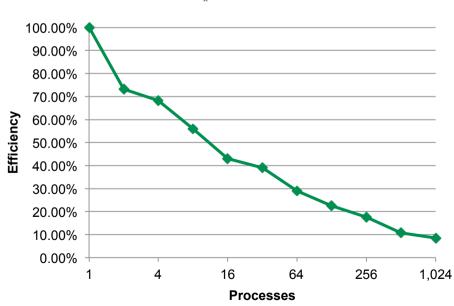
Result: rabbit ventricle - FHN model



- Approximately 470k points
 - No output, 800 time steps
 - T₁ ~ 8900s, 11s per time step
- FHN model has 2 ODEs/cell



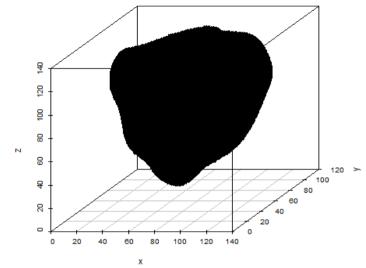


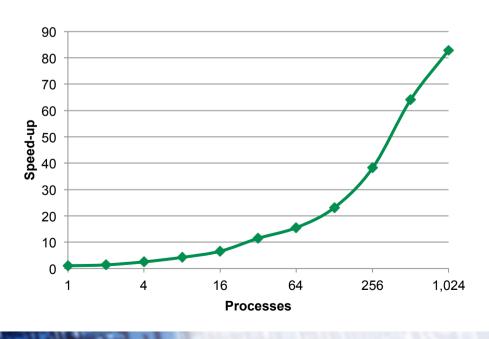


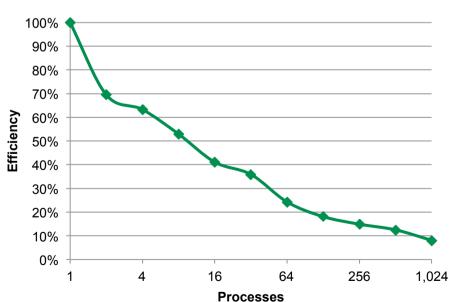
Result: rabbit ventricle - CRN model



- Approximately 470k points
 - No output, 10,000 time steps
 - T₁ ~ 12,273, ~1.2s per time step
- CRN model has 22 ODEs/cell



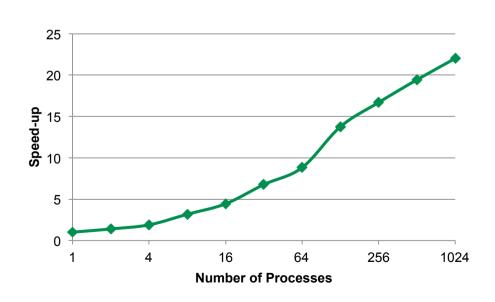


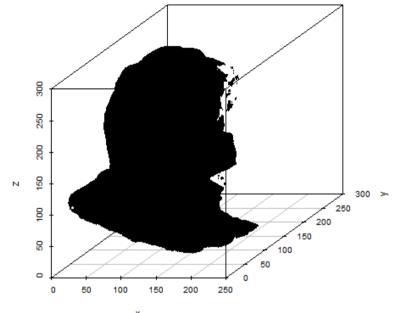


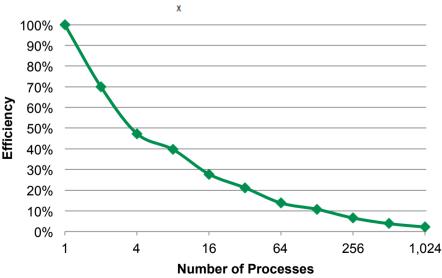
Result: human atrium



- Approximately 19M points
 - No output, 2000 time steps
 - T₁ ~ 5359, ~2.7s per time step
 - Compiled with –O3





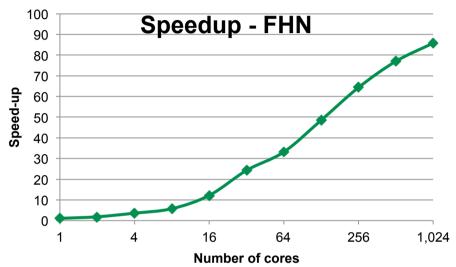


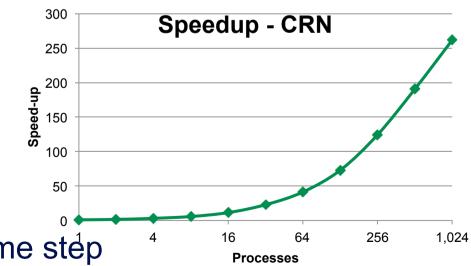
Result: Box3D

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- Big box with biophysical realistic models
- Have a 302x302x302 grid
- FHN has 2 ODEs/cell
- CRN has 22 ODEs/cell
- No output
- FHN: 800 time steps
- FHN T₁ ~ 3430s,
 4.8s per time step
- CRN:200 time steps







Conclusions



- Performance depends on:
 - The model used
 - How much fill there is
 - Performance quickly saturates as more processes are added
- You will get a definite benefit from using more processors
 - Do not have to go to HPC systems to observe this
 - Normally you want to achieve a performance of about 70%
- Need to identify where parallel performance bottlenecks are

humanAtrium bbs script



